

Signal Processing and Speech Communication Laboratory—Prof. G. Kubin  
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## Exam *Adaptive Systems* on 2006/11/25

Name

MatrNr.

StudKennz.

Exam duration: 120 minutes

Maximum points: 100

Allowed material: mathematical formulary, calculator

**You have to return this document after the exam! Good luck!**

### Problem 1 (33 Points)

Consider the following identification problem:

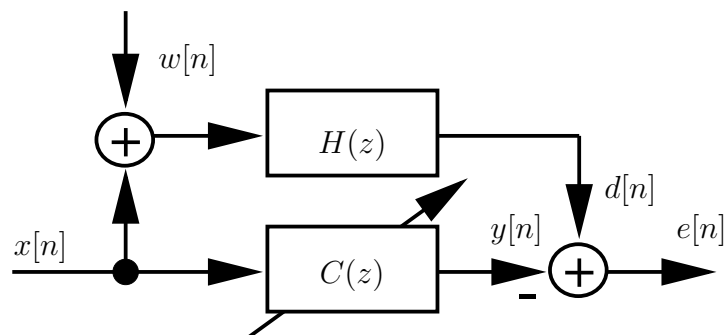
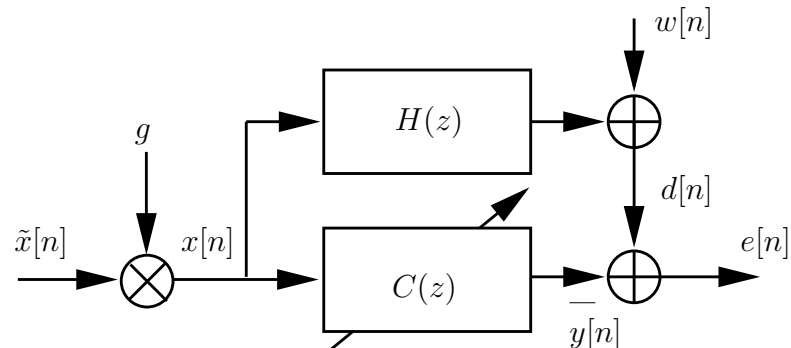


Figure 1: Adaptive system

Assume that the process  $w[n]$  and the process  $x[n]$  are statistically independent.

- Derive the Wiener solution  $\mathbf{c}_{opt}$  for the adaptive filter  $C(z)$ .
- Derive the minimum mean-square error (MMSE)  $J_{min}$  of the system.
- Assume that  $w[n]$  is a white-noise process with zero mean and variance  $\sigma_w^2=0.01$ ,  $H(z)$  is a FIR filter with  $H(z) = 1 + 0.5z^{-1} + 0.5z^{-2}$ , and the adaptive filter  $C(z)$  is of order 2, i.e., consists of 3 coefficients. Determine  $J_{min}$  for this configuration.

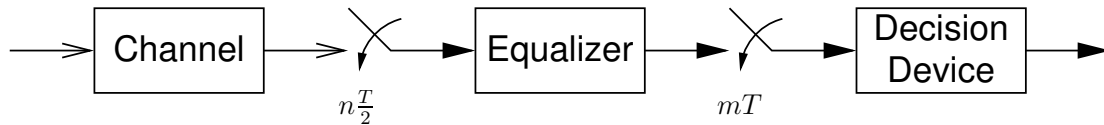
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**Problem 2 (33 Points)**


The projection algorithm should be used to identify the system  $H(z)$  with the impulse response  $h[n] = h_0\delta[n]$ . The input signal  $x[n]$  is the white-noise signal  $\tilde{x}[n]$  with zero mean and variance  $\sigma_x^2 = 1$  multiplied by the gain factor  $g$ . The adaptive transversal filter  $C(z)$  is of order 0, i.e.,  $c[n] = c_0\delta[n]$ . The desired signal  $d[n]$  consists of the filter output and an additive white-noise signal  $w[n]$  with zero mean and variance  $\sigma_w^2$ . Please notice that  $x[n]$  is the input signal for the system identification.

- (a) Write down the *projection algorithm* for the given system.
- (b) Express the coefficient  $c_0[n]$  of the projection algorithm in relation to the impulse response  $h[n]$  and the noise  $w[n]$  (Hint: Express the error  $e[n]$  by the input signal  $x[n]$ , the filter coefficients of the impulse responses  $h[n]$  and  $c[n]$ , and the noise  $w[n]$ ).
- (c) Determine the misalignment vector  $\mathbf{v}[n] = \mathbf{c}[n] - \mathbf{c}_{opt}$  of the projection algorithm for the given system, where  $\mathbf{c}_{opt}$  is the vector of the Wiener solution. Use the result from (b).
- (d) Describe the influence of the gain  $g$  (larger, equal, and smaller 1) regarding the misalignment vector  $v[n]$ .

### Problem 3 (34 Points)



Consider the  $\frac{T}{2}$ -fractionally-spaced equalizer illustrated above where the incoming signal is sampled at a rate twice the symbol rate. The decision device is synchronized with the *even-indexed* samples.

The discrete-time FIR description of the communication channel is

$$H(z) = h_0 + h_1 z^{-1} + h_2 z^{-2} = 1 + 2z^{-1} + 3/4 z^{-2}$$

where the unit delay  $z^{-1}$  corresponds to  $\frac{T}{2}$ .

(a) Design a minimum MSE equalizer of order 1 (2 coefficients)

$$C(z) = c_0 + c_1 z^{-1}$$

so that the cascade of channel and equalizer yields  $H(z)C(z) = 1$  (delay-free perfect equalization).

(b) Repeat the last task to design a minimum MSE equalizer that yields  $H(z)C(z) = z^{-2}$  (perfect equalization with delay).

(c) Calculate the noise gain of both solutions. Which solution would you prefer and why?