

Relevance Vector Machines

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- Machine Learning as function approximation.
 Kernel methods.
 - ⊳ Sparsity and SVM.
 - Relevance Vector Machines.
 - ⊳ Problem formulation (regression).
 - \triangleright Priors.
 - \triangleright Inference.
 - ► RVM example.
 - Conclusions.





The goal of **supervised machine learning** is to use a training set S_x to "learn" a function $y(\cdot)$ that correctly "explains" observations/targets t given input data x, i.e.,

$$\boldsymbol{t} = y(\boldsymbol{x}), \ \boldsymbol{x} \in S_x$$



Consider the following example: given a set of points (x_i, t_i) find the function y(x), such that $t_i = y(x_i)$





This is one possible solution





Here is another, and quite a different one. Which solution to choose?



One possible solution is the following:

- Choose a certain hypothesis space $\mathcal{H}, y \in \mathcal{H}$.
- Impose constrains on the function y. In most cases it is the norm of the sought function y.
- ► Find the regularized solution.

$$\min_{y \in \mathcal{H}} \left\{ \frac{1}{N} \sum_{i=1}^{N} V(\boldsymbol{t}_i, y(\boldsymbol{x}_i)) + \lambda \|y\|^2 \right\}$$



It can be shown that the solution to this regularization could be written in the following form

$$y(\boldsymbol{x}) = \sum_{i=1}^{N} w_i \cdot K(\boldsymbol{x}, \boldsymbol{x_i})$$

 $K(\cdot, \cdot)$ is called the kernel. Usually the kernel $K(\cdot, \cdot)$ is associated with the corresponding hypothesis space \mathcal{H} .



With as many parameters as training examples, we would expect severe over-fitting. By setting some of the weights to zero this can be avoided. Thus, the model becomes *sparse*.

The direct posterior of such an approach leads to Support Vector Machines (SVMs).

In the SVM case, every x_i for which $w_i \neq 0$ becomes a support vector.



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In a nutshell, RVM is a Bayesian approach to estimate the parameters w_i of the model

$$y(\boldsymbol{x}, \boldsymbol{w}) = \sum_{i=1}^{N} w_i \cdot K(\boldsymbol{x}, \boldsymbol{x}_i) + w_0$$

and introduce sparsity.

- RVM is not a Bayesian interpretation of SVM but rather the method on its own, which adopts the same functional form.
- The kernel functions in RVM are treated simply as a set of basis functions without many restrictions imposed on SVM kernels.
- ► RVM uses a fully probabilistic framework.
- RVM uses significantly fewer basis functions then SVM.



 $\{\boldsymbol{x}_n, t_n\}_{n=1}^N$ is a training data set.

The targets are samples from the model with additive noise

$$t_n = y(\boldsymbol{x}_n; \boldsymbol{w}) + \epsilon_n$$

where

$$y(\boldsymbol{x}, \boldsymbol{w}) = \sum_{i=1}^{N} w_i \cdot K(\boldsymbol{x}, \boldsymbol{x}_i) + w_0$$



 ϵ_n is assumed to be zero-mean Gaussian noise process with variance σ^2 . Thus,

$$p(t_n | \boldsymbol{x}) = \mathcal{N}(t_n | y(\boldsymbol{x}_n), \sigma^2)$$

We rewrite the kernel sum in the following form:

$$\sum_{i=1}^{N} w_i \cdot K(\boldsymbol{x}, \boldsymbol{x}_i) + w_0 = \sum_{i=0}^{N} w_i \cdot \phi_i(\boldsymbol{x}) = \boldsymbol{w}^T \boldsymbol{\phi}(\boldsymbol{x})$$

where $\phi_0(\boldsymbol{x}) \equiv 1$



The likelihood of the complete data set can be written as follows:

$$p(\boldsymbol{t}|\boldsymbol{w},\sigma^2) = \left(\frac{1}{2\pi\sigma^2}\right)^{\frac{N}{2}} \exp\left\{-\frac{1}{2\sigma^2}\|\boldsymbol{t}-\boldsymbol{\Phi}\boldsymbol{w}\|^2\right\}$$

where

$$t = [t_1, t_2, ..., t_N]^T$$
, $N \times 1$ vector;
 $w = [w_0, w_2, ..., w_N]^T$; $(N + 1) \times 1$ vector;
 $\Phi = [\phi(x_1), \phi(x_2), ..., \phi(x_N)]^T$, $N \times (N + 1)$
matrix.



To avoid over-fitting, we "constrain" the parameters by defining an explicit prior over them.

$$p(\boldsymbol{w}|\boldsymbol{\alpha}) = \prod_{i=0}^{N} \mathcal{N}(w_i|0, \alpha_i^{-1})$$

with α being a vector of (N+1) hyperparameters.



To complete the specification of priors, we define a hyperprior over α as well as over the noise variance σ^2 .

$$p(\boldsymbol{\alpha}) = \prod_{i=0}^{N} \operatorname{Gamma}(\alpha_{i}|a, b)$$

 $p(\beta) = \text{Gamma}(\beta|c,d)$, where $\beta \equiv \sigma^{-2}$



Priors - graphical model





Learning RVM



How it should work: for the given test point x_* we should correctly predict the target t_*

$$p(t_*|\boldsymbol{t}) = \int p(t_*|\boldsymbol{w}, \boldsymbol{\alpha}, \sigma^2) \cdot p(\boldsymbol{w}, \boldsymbol{\alpha}, \sigma^2|\boldsymbol{t}) d\boldsymbol{w} d\boldsymbol{\alpha} d\sigma^2$$

Where $p(oldsymbol{w},oldsymbol{lpha},\sigma^2|oldsymbol{t})$ is

$$p(\boldsymbol{w}, \boldsymbol{\alpha}, \sigma^2 | \boldsymbol{t}) = \frac{p(\boldsymbol{t} | \boldsymbol{w}, \boldsymbol{\alpha}, \sigma^2) \cdot p(\boldsymbol{w}, \boldsymbol{\alpha}, \sigma^2)}{p(\boldsymbol{t})}$$

This form has no analytical solution.



This is the way around :



The posterior over the weight is expressed as

$$p(\boldsymbol{w}|\boldsymbol{t}, \boldsymbol{\alpha}, \sigma^2) = \frac{p(\boldsymbol{t}|\boldsymbol{w}, \sigma^2) \cdot p(\boldsymbol{w}|\alpha)}{\int p(\boldsymbol{t}|\boldsymbol{w}, \sigma^2) \cdot p(\boldsymbol{w}|\alpha) d\boldsymbol{w}}$$

Here, all the PDFs are Gaussian. Thus, we can obtain the analytical expression for the posterior PDF over the weights.



The posterior over the weights is expressed as

$$p(\boldsymbol{w}|\boldsymbol{t},\boldsymbol{\alpha},\sigma^2) = \frac{1}{(2\pi)^{\frac{N+1}{2}} |\boldsymbol{\Sigma}|^{\frac{1}{2}}} \exp\left\{-\frac{(\boldsymbol{w}-\boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\boldsymbol{w}-\boldsymbol{\mu})}{2}\right\}$$

where

$$egin{aligned} oldsymbol{\Sigma} &= (\sigma^{-2} oldsymbol{\Phi}^T oldsymbol{\Phi} + oldsymbol{A})^{-1} \ oldsymbol{A} &= diag(lpha_0, lpha_1, \dots, lpha_N) \ oldsymbol{\mu} &= \sigma^{-2} oldsymbol{\Sigma} oldsymbol{\Phi}^T oldsymbol{t} \end{aligned}$$



In case of $p(\alpha, \sigma^2 | t)$ we have to adopt some approximations.

We exchange $p(\alpha, \sigma^2 | t)$ with a delta function at its mode in a sense that

$$p(t_*|\boldsymbol{t})_{MP} = \int p(t_*|\boldsymbol{\alpha}, \sigma^2) \delta(\boldsymbol{\alpha}_{MP}, \sigma^2_{MP}) d\boldsymbol{\alpha} d\sigma^2 \approx \int p(t_*|\boldsymbol{\alpha}, \sigma^2) p(\boldsymbol{\alpha}, \sigma^2|\boldsymbol{t}) d\boldsymbol{\alpha} d\sigma^2 = p(t_*|\boldsymbol{t})$$

is a good approximation



Relevance vector "learning" thus becomes the search for the hyperparameters that maximize

$$p(\boldsymbol{\alpha}, \sigma^2 | \boldsymbol{t}) \propto p(\boldsymbol{t} | \boldsymbol{\alpha}, \sigma^2) p(\boldsymbol{\alpha}) p(\sigma^2)$$

with respect to α and σ^2 .

In case of uniform priors, we only have to maximize the term

$$p(\boldsymbol{t}|\boldsymbol{\alpha},\sigma^{2}) = \int p(\boldsymbol{t}|\boldsymbol{w},\sigma^{2})p(\boldsymbol{w}|\boldsymbol{\alpha})d\boldsymbol{w} =$$
$$= \frac{(2\pi)^{-\frac{N}{2}}}{|\sigma^{2}\mathbf{I} + \boldsymbol{\Phi}\mathbf{A}^{-1}\boldsymbol{\Phi}^{T}|^{\frac{1}{2}}} \exp\left\{-\frac{\boldsymbol{t}^{T}(\sigma^{2}\mathbf{I} + \boldsymbol{\Phi}\mathbf{A}^{-1}\boldsymbol{\Phi}^{T})^{-1}\boldsymbol{t}}{2}\right\}$$

Its maximization is known as type-II maximum likelihood method.



In case of non-uniform priors, the maximization is a bit more complex, but finally leads to the iterative re-estimation formulas:

$$\alpha_i^{new} = \frac{(1 - \alpha_i \Sigma_{ii}) + 2a}{\mu_i^2 + 2b},$$

$$(\sigma^2)^{new} = \frac{\|\boldsymbol{t} - \boldsymbol{\Phi}\boldsymbol{\mu}\|^2 + 2d}{N - \sum_i (1 - \alpha_i \Sigma_{ii}) + 2c},$$

 Σ_{ij} and μ_i are the scalar values taken from the corresponding matrix and vector.

$$\alpha_{i}^{new} = \frac{(1 - \alpha_{i}\Sigma_{ii}) + 2a}{\mu_{i}^{2} + 2b},$$
$$(\sigma^{2})^{new} = \frac{\|\boldsymbol{t} - \boldsymbol{\Phi}\boldsymbol{\mu}\|^{2} + 2d}{N - \sum_{i}(1 - \alpha_{i}\Sigma_{ii}) + 2c},$$

$$egin{aligned} oldsymbol{\Sigma} &= (\sigma^{-2} oldsymbol{\Phi}^T oldsymbol{\Phi} + oldsymbol{A})^{-1} \ oldsymbol{A} &= diag(lpha_0, lpha_1, \dots, lpha_N) \ oldsymbol{\mu} &= \sigma^{-2} oldsymbol{\Sigma} oldsymbol{\Phi}^T oldsymbol{t} \end{aligned}$$

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A large proportion of α_i are driven to large values (in principle they become infinite) during the learning procedure.

Thus, $p(w_i | t, \alpha, \sigma^2)$ becomes highly peaked around zero – i.e. we are *a posteriori* "certain" that these w_i are zero.

The vectors \boldsymbol{x}_i for which w_i are not zero are called relevance vectors.

Having found the maximizing values α_{MP} and σ_{MP}^2 , we can now compute predictions

$$p(t_*|\boldsymbol{t}, \boldsymbol{\alpha}_{MP}, \sigma_{MP}^2) =$$
$$= \int p(t_*|\boldsymbol{w}, \sigma_{MP}^2) \cdot p(\boldsymbol{w}|\boldsymbol{t}, \boldsymbol{\alpha}_{MP}, \sigma_{MP}^2) d\boldsymbol{w}$$

Both terms in the integrand are Gaussian, thus

the result can be readily computed to be

$$p(t_*|\boldsymbol{t}, \boldsymbol{\alpha}_{MP}, \sigma^2_{MP}) = \mathcal{N}(t_*|y_*, \sigma^2_*)$$

with

$$y_* = \boldsymbol{\mu}^T \boldsymbol{\phi}(\boldsymbol{x}_*)$$
$$\sigma_*^2 = \sigma_{MP}^2 + \boldsymbol{\phi}(\boldsymbol{x}_*)^T \boldsymbol{\Sigma} \boldsymbol{\phi}(\boldsymbol{x}_*)$$



RVM example



- ► Generalization is typically very good.
- ► Learned models are typically highly sparse.
- There are no constraints imposed on the basis functions.
- Different input scales for input variable are possible.

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