



Exact Inference

Marián Képesi
Signal Processing and Speech Communication Lab.

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- **Outline:**
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- Notation conventions
- Belief networks
- Secondary structures
- Integration of evidence
- Optimization opportunities
- Conclusions



• Notation conventions

- Variables .. (A, B, C)
- values .. (a, b, c)
 - a is an instantiation of A
- Sets of variables: .. (A, B, C)
 - their instantiations $(\mathbf{a}, \mathbf{b}, \mathbf{c})$
 - \mathbf{x} is an instantiation of \mathbf{X}

• Probability distributions

$$\sum_{\mathbf{x}} P(\mathbf{x}) = 1$$

• Conditional probabilities

$$\sum_{\mathbf{x}} P(\mathbf{x} | \mathbf{y}) = 1$$

• Notation conventions

- Potentials .. defined over a set of variables \mathbf{X} ,
 - a function that maps each instantiation \mathbf{x} into a nonnegative real number
- 1. Operation on potentials: Marginalization

The **marginalization** of $\phi_{\mathbf{Y}}$ into \mathbf{X} is a potential $\phi_{\mathbf{X}}$, where each $\phi_{\mathbf{X}}(\mathbf{x})$ is computed as follows:

1. Identify the instantiations $\mathbf{y}_1, \mathbf{y}_2, \dots$ that are consistent with \mathbf{x} .
2. Assign to $\phi_{\mathbf{X}}(\mathbf{x})$ the sum $\phi_{\mathbf{Y}}(\mathbf{y}_1) + \phi_{\mathbf{Y}}(\mathbf{y}_2) + \dots$

This marginalization is denoted as follows:

$$\phi_{\mathbf{X}} = \sum_{\mathbf{Y} \setminus \mathbf{X}} \phi_{\mathbf{Y}}.$$

Belief networks

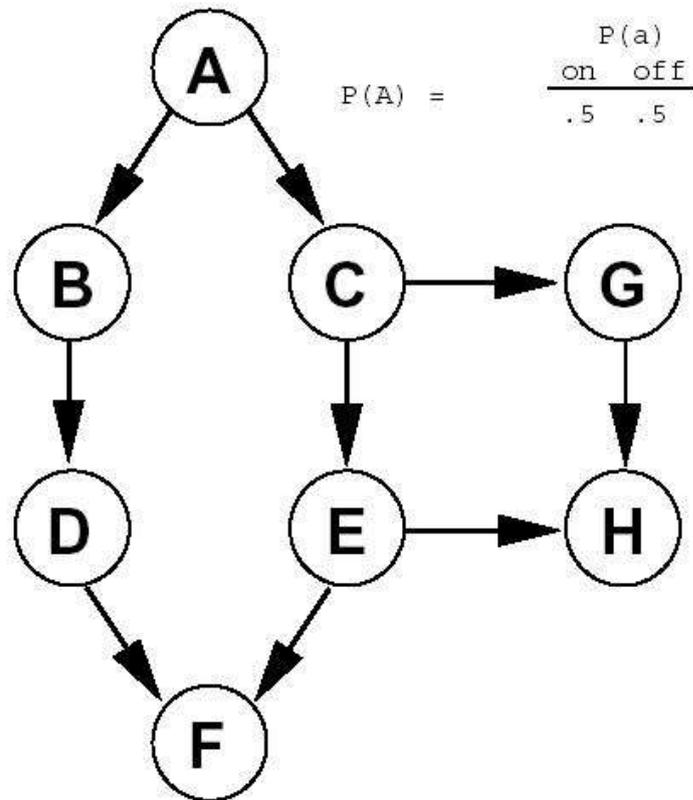
- 2. Operation on potentials: Multiplication

$$\phi_{\mathbf{Z}} = \phi_{\mathbf{X}}\phi_{\mathbf{Y}}$$

Example: $U = \{A, B, \dots, G, H\}$
each having values {on, off}

Example of probabilistic inference:
Compute the probability that $A = \text{on}$,
given the knowledge that $C = \text{on}$ and $E = \text{off}$.

Belief networks



$$P(A) = \begin{array}{c|cc} & \text{on} & \text{off} \\ \hline P(a) & .5 & .5 \end{array}$$

$$P(B|A) = \begin{array}{c|cc} & \text{on} & \text{off} \\ \hline a & P(b|a) & \\ \hline \text{on} & .5 & .5 \\ \text{off} & .4 & .6 \end{array}$$

$$P(C|A) = \begin{array}{c|cc} & \text{on} & \text{off} \\ \hline a & P(c|a) & \\ \hline \text{on} & .7 & .3 \\ \text{off} & .2 & .8 \end{array}$$

$$P(D|B) = \begin{array}{c|cc} & \text{on} & \text{off} \\ \hline a & P(d|b) & \\ \hline \text{on} & .9 & .1 \\ \text{off} & .5 & .5 \end{array}$$

$$P(E|C) = \begin{array}{c|cc} & \text{on} & \text{off} \\ \hline a & P(e|c) & \\ \hline \text{on} & .3 & .7 \\ \text{off} & .6 & .4 \end{array}$$

$$P(F|DE) = \begin{array}{cc|cc} & d & e & P(f|de) & \\ \hline & & & \text{on} & \text{off} \\ \hline \text{on} & \text{on} & & .01 & .99 \\ \text{on} & \text{off} & & .01 & .99 \\ \text{off} & \text{on} & & .01 & .99 \\ \text{off} & \text{off} & & .99 & .01 \end{array}$$

$$P(G|C) = \begin{array}{c|cc} & \text{on} & \text{off} \\ \hline c & P(g|c) & \\ \hline \text{on} & .8 & .2 \\ \text{off} & .1 & .9 \end{array}$$

$$P(H|EG) = \begin{array}{cc|cc} & g & h & P(h|eg) & \\ \hline & & & \text{on} & \text{off} \\ \hline \text{on} & \text{on} & & .05 & .95 \\ \text{on} & \text{off} & & .95 & .05 \\ \text{off} & \text{on} & & .95 & .05 \\ \text{off} & \text{off} & & .95 & .05 \end{array}$$

Example of a directed acyclic graph (DAG).



PPTC

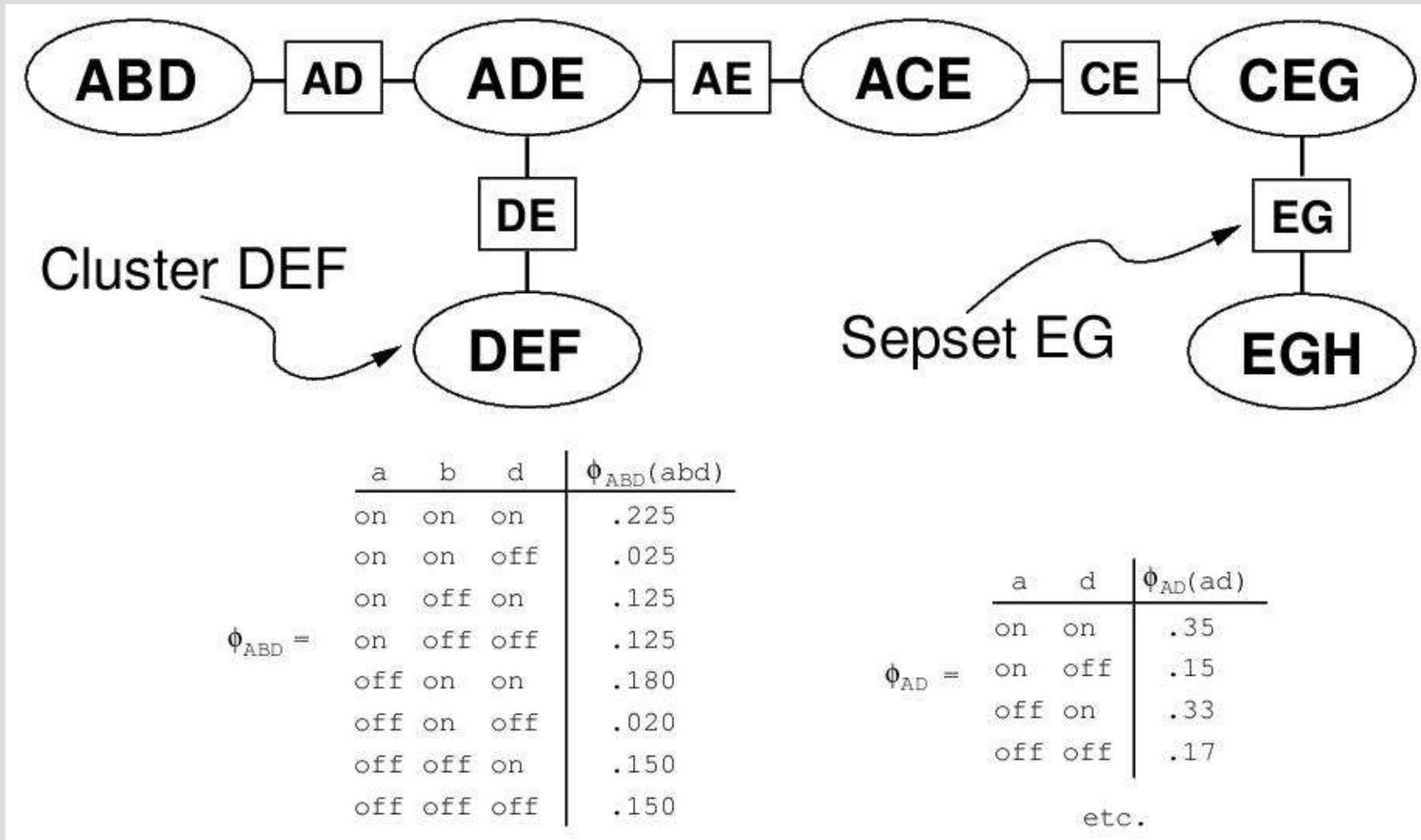
Probability Propagation in Trees of Clusters (PPTC)

(Lauritzen, Spiegelhalter - 1988, Jensen-1990)

PPTC is a method for performing probabilistic inference on a belief network.

In general, probabilistic inference on a belief network is the process of computing $P(V = v \mid \mathbf{E} = \mathbf{e})$, or simply $P(v \mid \mathbf{e})$, where v is a value of a variable V and \mathbf{e} is an assignment of values to a set of variables \mathbf{E} in the belief network.

Secondary Structures



Example of a secondary struct.



Secondary Structures

Experts typically use belief networks to encode their domain, but PPTC performs probabilistic inference on a secondary structure

Secondary structure contains a graphical and a numerical component

Graphical:

- Each node in “Tau” is a **cluster**.
- Each edge in “Tau” is labeled with the intersection of the adjacent clusters; these labels are called separator sets, or **sepsets**.

Numerical:

- described using the notion of a **belief potential**. A belief potential is a function that maps each instantiation of a set of variables into a real number

Secondary structure

Each cluster \mathbf{X} is associated with a belief potential $\phi_{\mathbf{x}}$,

Each sepset \mathbf{S} is associated with a belief potential $\phi_{\mathbf{s}}$.

!! Belief potentials are not arbitrarily specified; they must satisfy the following constraints:

a) $\phi_{\mathbf{s}}$ is consistent:

$$\sum_{\mathbf{X} \setminus \mathbf{S}} \phi_{\mathbf{x}} = \phi_{\mathbf{s}} \quad \longrightarrow \quad \phi_{AD} = \sum_B \phi_{ABD}$$

b) The belief potentials encode the joint distribution $P(\mathbf{U})$ of the belief network

$$P(\mathbf{U}) = \frac{\prod_i \phi_{\mathbf{x}_i}}{\prod_j \phi_{\mathbf{s}_j}}, \quad \longrightarrow \quad P(\mathbf{U}) = \frac{\phi_{ABD} \phi_{ACE} \phi_{ADE} \phi_{CEG} \phi_{DEF} \phi_{EGH}}{\phi_{AD} \phi_{AE} \phi_{CE} \phi_{DE} \phi_{EG}}$$

A key step in PPTC is the construction of a secondary structure that satisfies the above constraints



Secondary structure

...then for each **cluster** holds: $f_{i_{\mathbf{x}}} = P(\mathbf{X})$
therefore we can compute the probab. distr. of any variable:

$$P(V) = \sum_{\mathbf{x} \setminus \{V\}} \phi_{\mathbf{x}}$$

secondary structure in the **literature**:

join tree, junction tree, tree of belief universes, cluster tree, and clique tree.

we use the term **join tree** to refer to the graphical component, and the term **join tree potential** to refer generically to a cluster or sepset belief potential. We will also use the term join tree to refer to the entire secondary structure.



Building join trees

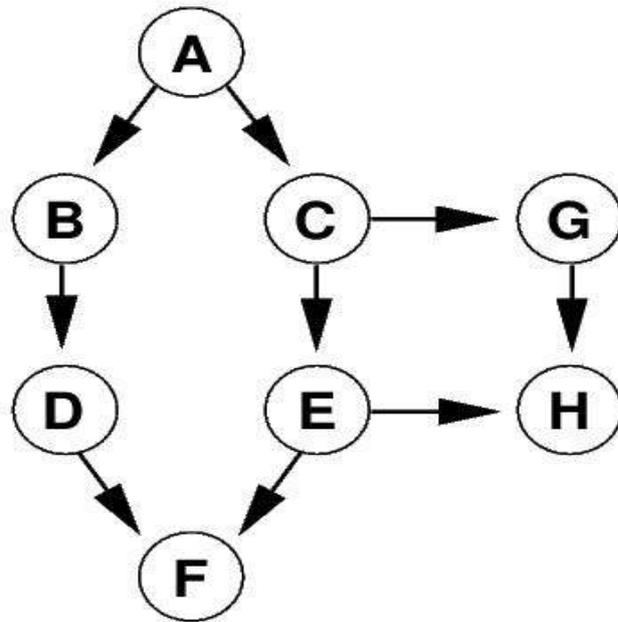
We begin with the DAG of a belief network, and apply a series of graphical transformations:

1. Construct an undirected graph, called a **moral graph**, from the DAG.
2. Selectively add arcs to the moral graph to form a **triangulated graph**.
3. From the triangulated graph, identify select subsets of nodes, called **cliques**.
4. Build a join tree, starting with the cliques as clusters: connect the clusters to form an undirected tree satisfying the join tree property, inserting the appropriate sepsets.

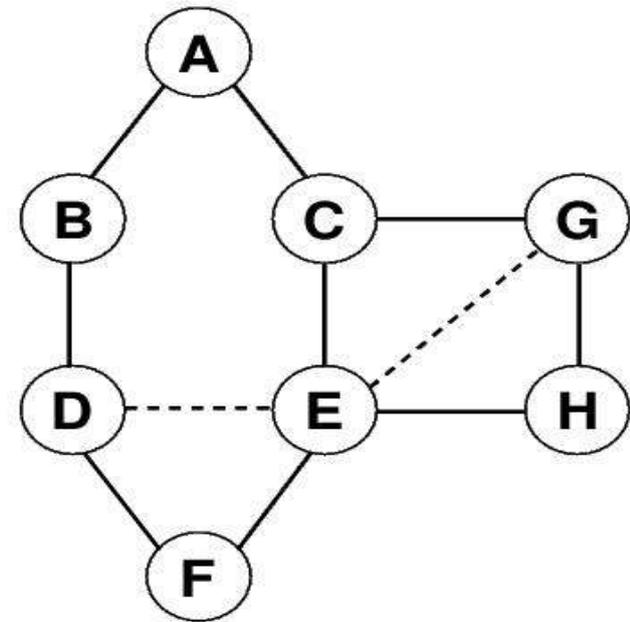
Steps 2 and 4 are nondeterministic; consequently, many different join trees can be built from the same DAG.

Building join trees

Moral Graph:



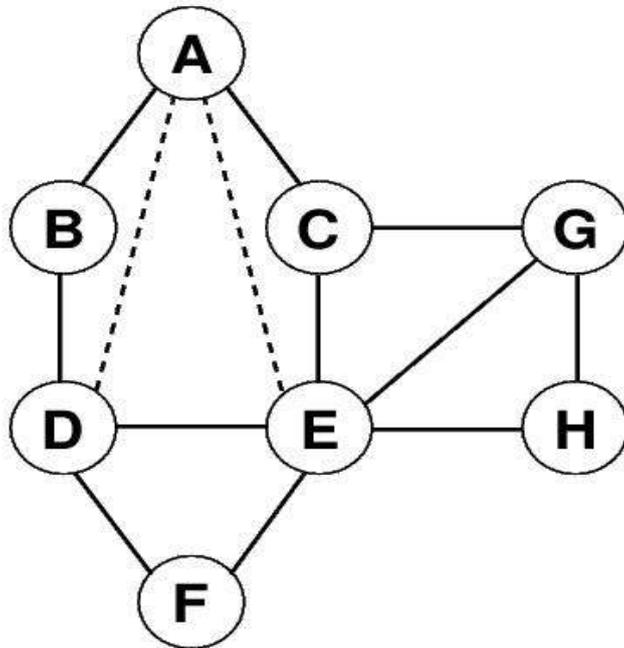
Belief-Network Structure



Moral Graph

Building join trees

Triangulated Graph:



Triangulated Graph

Eliminated Vertex	Induced Cluster	Edges Added
H	EGH	none
G	CEG	none
F	DEF	none
C	ACE	(A, E)
B	ABD	(A, D)
D	ADE	none
E	AE	none
A	A	none

Elimination Ordering

The criterion for selecting nodes to remove is now stated as follows:

- Choose the node that causes the least number of edges to be added in Step 2b, breaking ties by choosing the node that induces the cluster with the smallest weight.⁷



Building join trees

Identifying cliques:

A clique in an undirected graph G is a **subgraph of G** that is complete and maximal. **Complete** means that every pair of distinct nodes is connected by an edge. **Maximal** means that the clique is not properly contained in a larger, complete subgraph.

It can be done during the triangulation phase by saving **each induced cluster that is not a subset** of any previously saved cluster.

Revisiting our example:
cliques of the triangulated graph: EGH, CEG, DEF, ACE, ABD, and ADE..



Building join trees

Building an **optimal tree**:

0. one single clique = **one tree**., n trees.
1. create candidate sepsets ($n-1$)
2. select them based on the criterion below..
3. Insert the sepset S_{XY} between the cliques **X** and **Y**
only if **X** and **Y** are on different trees in the forest.

For the resulting clique tree *to satisfy the join tree property*, we must choose the candidate **sepset with the largest mass**.

When two or more sepsets of equal mass can be chosen, we can *optimize the inference time* on the resulting join tree by breaking the tie as follows: choose the candidate **sepset with the smallest cost**.

Building join trees

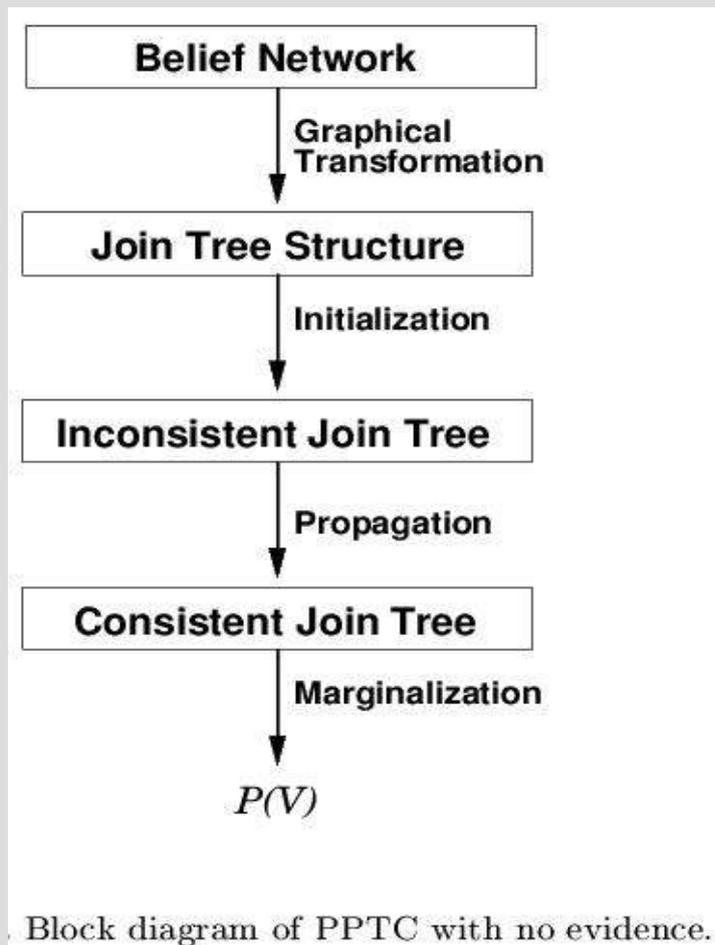
Building an **optimal tree**:

- The **mass** of a sepset S_{XY} is the number of variables it contains, or the number of variables in $X \cap Y$.
- The **cost** of a sepset S_{XY} is the weight of X plus the weight of Y , where *weight* is defined as follows:
 - The **weight** of a variable V is the number of values of V .
 - The **weight** of a set of variables X is the product of the weights of the variables in X .

If an **empty candidate sepset** is created, the search is terminated.

Principles of inference

We provide procedures for computing the join tree's numerical component, so that it satisfies the conditions



Note: computing $P(V)$ corresponds to probabilistic inference in the context of **no evidence**.

We address later the more general problem of computing $P(V | \mathbf{e})$, in the context of evidence \mathbf{e} .

Principles of inference

I. Initialization:

1. For each cluster and sepset \mathbf{X} , set each $\phi_{\mathbf{X}}(\mathbf{x})$ to 1:

$$\phi_{\mathbf{X}} \leftarrow 1.$$

2. For each variable V , perform the following: Assign to V a cluster \mathbf{X} that contains \mathbf{F}_V ;¹¹ call \mathbf{X} the **parent cluster** of \mathbf{F}_V . Multiply $\phi_{\mathbf{X}}$ by $P(V | \Pi_V)$:

$$\phi_{\mathbf{X}} \leftarrow \phi_{\mathbf{X}} P(V | \Pi_V).$$

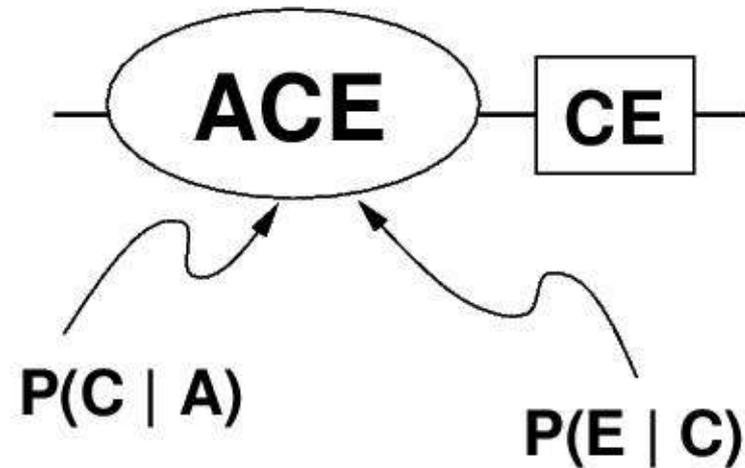
init. satisfies the joint distrib.:

$$\frac{\prod_{i=1}^N \phi_{\mathbf{X}_i}}{\prod_{j=1}^{N-1} \phi_{\mathbf{S}_j}} = \frac{\prod_{k=1}^Q P(V_k | \mathbf{C}_{V_k})}{1} = P(\mathbf{U})$$

Principles of inference

I. Initialization:

..of cluster ACE and stepset CE:



$P(C A) =$	a	$P(c a)$	
		on	off
	on	.7	.3
	off	.2	.8
$P(D B) =$	a	$P(d b)$	
		on	off
	on	.9	.1
	off	.5	.5
$P(E C) =$	a	$P(e c)$	
		on	off
	on	.3	.7
	off	.6	.4

			ϕ_{ACE}	ϕ_{CE}
a	c	e	Initial Values	
on	on	on	$1 \times .7 \times .3 = .21$	1
on	on	off	$1 \times .7 \times .7 = .49$	1
on	off	on	$1 \times .3 \times .6 = .18$	1
on	off	off	$1 \times .3 \times .4 = .12$	1
off	on	on	$1 \times .2 \times .3 = .06$	1
off	on	off	$1 \times .2 \times .7 = .14$	1
off	off	on	$1 \times .8 \times .6 = .48$	1
off	off	off	$1 \times .8 \times .4 = .32$	1
				etc.

Principles of inference

II. Global propagation:

After initializing the join tree potentials we perform **global propagation** in order to make them *locally consistent* (slide 10).

Global propagation consists of a series of **local manipulations**, called **message passes**, that occur between a cluster **X** and a neighboring cluster **Y**.

Global propagation causes each cluster to pass a message **to each of its neighbors**; these message passes are **ordered** so that each message pass will preserve the consistency introduced by previous message passes. When global propagation is completed, each cluster-sepset pair is *consistent*, and the join tree is *locally consistent*. (pp.9)

Principles of inference

II. Global propagation:

Single message pass:

Consider two adjacent clusters \mathbf{X} and \mathbf{Y} with sepset \mathbf{R} :

1. Projection. Assign a new table to \mathbf{R} , saving the old table:

$$\phi_{\mathbf{R}}^{old} \leftarrow \phi_{\mathbf{R}}.$$

$$\phi_{\mathbf{R}} \leftarrow \sum_{\mathbf{X} \setminus \mathbf{R}} \phi_{\mathbf{X}}. \quad (1)$$

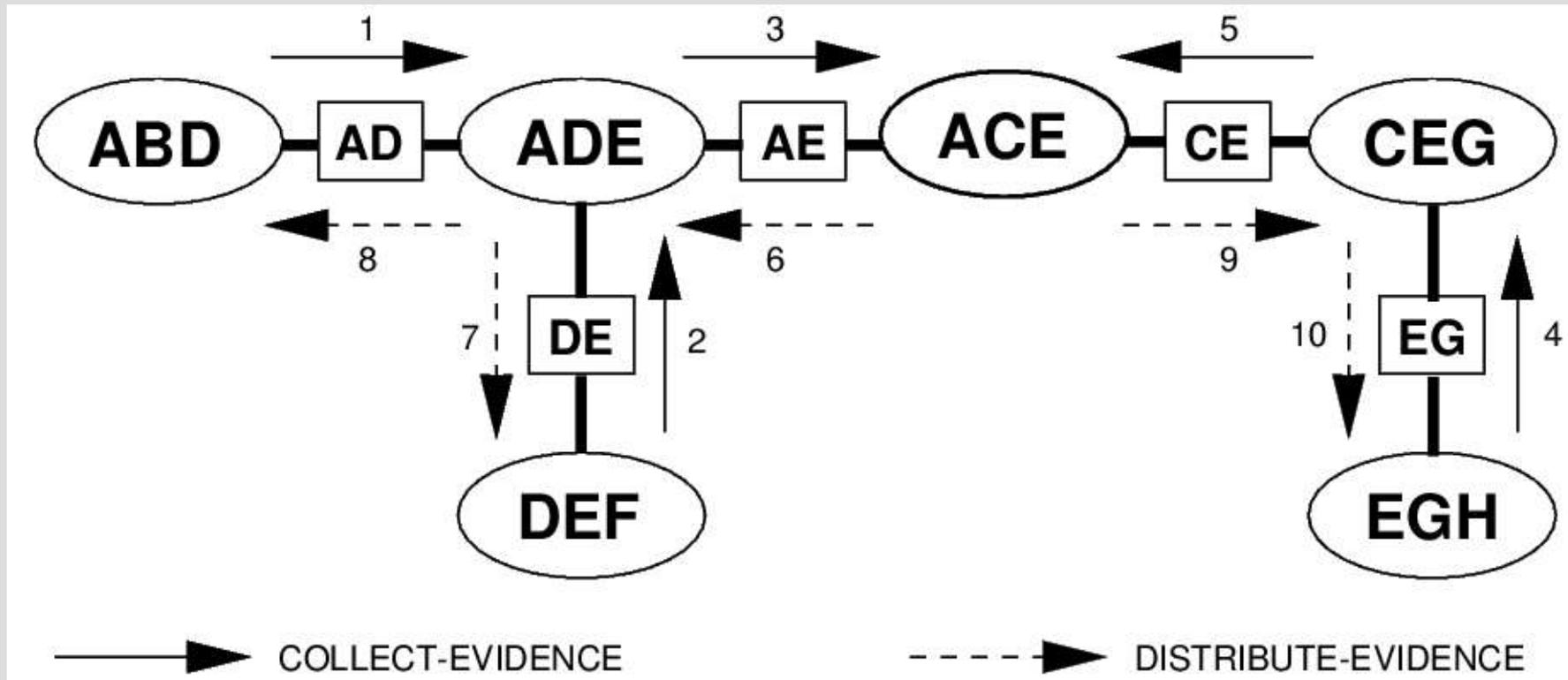
2. Absorption. Assign a new table to \mathbf{Y} , using both the old and the new tables of \mathbf{R} :

$$\phi_{\mathbf{Y}} \leftarrow \phi_{\mathbf{Y}} \frac{\phi_{\mathbf{R}}}{\phi_{\mathbf{R}}^{old}}. \quad (2)$$

Principles of inference

II. Global propagation - Multiple message pass

- choosing an arbitrary cluster **X**
- performing $2(n-1)$ message passes



! a cluster passes a message to a neighbor only after it has received messages from all of its other neighbors, assuring local consistency.

III. Marginalization

once we have a consistent join tree, we can compute all $P(V)$:

1. Identify a cluster X that contains V
2. marginalize ϕ_x

$$P(V) = \sum_{\mathbf{x} \setminus \{V\}} \phi_x.$$

$$\phi_{ABD} =$$

a	b	d	$\phi_{ABD}(abd)$
on	on	on	.225
on	on	off	.025
on	off	on	.125
on	off	off	.125
off	on	on	.180
off	on	off	.020
off	off	on	.150
off	off	off	.150

$$P(A) = \sum_{BD} \phi_{ABD} =$$

a	$P(a)$
on	.225 + .025 + .125 + .125 = .500
off	.180 + .020 + .150 + .150 = .500

$$P(D) = \sum_{AB} \phi_{ABD} =$$

d	$P(d)$
on	.225 + .125 + .180 + .150 = .680
off	.025 + .125 + .020 + .150 = .320

Handling evidence

Observation – the simplest notion of evidence:

An observation is a statement of the form $V = v$. Collections of observations may be denoted by $\mathbf{E} = \mathbf{e}$, where \mathbf{e} is the instantiation of the set of variables \mathbf{E} .

Observations are also referred to as **hard evidence**.

To encode observation for PPTC we define **Likelihood** of V :

- If $V \in \mathbf{E}$ —that is, if V is observed—then assign each $\Lambda_V(v)$ as follows:

$$\Lambda_V(v) = \begin{cases} 1, & \text{when } v \text{ is the observed value of } V \\ 0, & \text{otherwise} \end{cases}$$

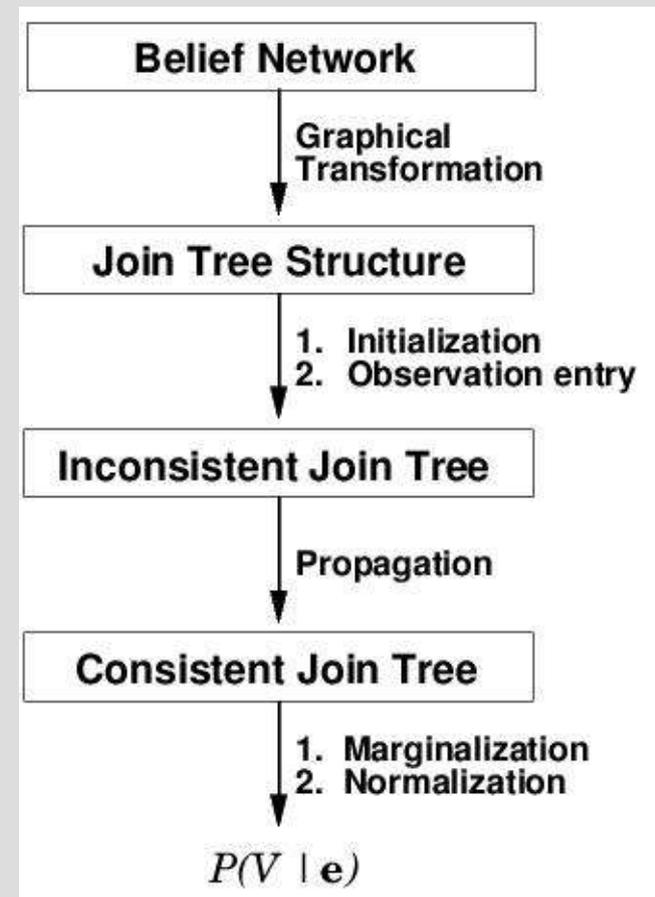
- If $V \notin \mathbf{E}$ —that is, if the value of V is unknown—then assign $\Lambda_V(v) = 1$ for each value v .

.. when there are no observations, the likelihood of each variable consists of all 1's.

Handling evidence

We use likelihoods to encode the observations $C = \text{on}$ and $E = \text{off}$ (C and E are variables from the join tree):

Variable V	$\Lambda_V(v)$	
	$v = \text{on}$	$v = \text{off}$
A	1	1
B	1	1
C	1	0
D	1	1
E	0	1
F	1	1
G	1	1
H	1	1



Handling evidence

1. Initialization with observation: 1 extra step:

1. For each cluster and sepset \mathbf{X} , set each $\phi_{\mathbf{X}}(\mathbf{x})$ to 1:

$$\phi_{\mathbf{X}} \leftarrow 1.$$

2. For each variable V :

(a) Assign to V a cluster \mathbf{X} that contains \mathbf{F}_V ; multiply $\phi_{\mathbf{X}}$ by $P(V | \Pi_V)$:

$$\phi_{\mathbf{X}} \leftarrow \phi_{\mathbf{X}} P(V | \Pi_V).$$

(b) Set each likelihood element $\Lambda_V(v)$ to 1:

$$\Lambda_V \leftarrow 1.$$

Handling evidence

2. Observation Entry:

Note: the likelihoods encode no observations.

We incorporate each observation $V = v$ by **encoding the observation as a likelihood**, and then incorporating this likelihood into the join tree, as follows:

1. Encode the observation $V = v$ as a likelihood Λ_V^{new} .
2. Identify a cluster \mathbf{X} that contains V .¹³
3. Update $\phi_{\mathbf{X}}$ and Λ_V :

$$\phi_{\mathbf{X}} \leftarrow \phi_{\mathbf{X}} \Lambda_V^{new}.$$

$$\Lambda_V \leftarrow \Lambda_V^{new}.$$

Now instead of computing $P(\mathbf{X})$ and $P(V)$,
we compute $P(\mathbf{X}; \mathbf{e})$ and $P(V; \mathbf{e})$, respectively.

Handling evidence

3. Normalizations:

After the join tree is made consistent through **global propagation**, we have, for each cluster (or sepset) \mathbf{X} , $fi_{\mathbf{x}} = P(\mathbf{X}; \mathbf{e})$.

Marginalizing a cluster potential $fi_{\mathbf{x}}$ into a variable V :

$$P(V, \mathbf{e}) = \sum_{\mathbf{x} \setminus \{V\}} \phi_{\mathbf{x}}.$$

.. by normalizing this:

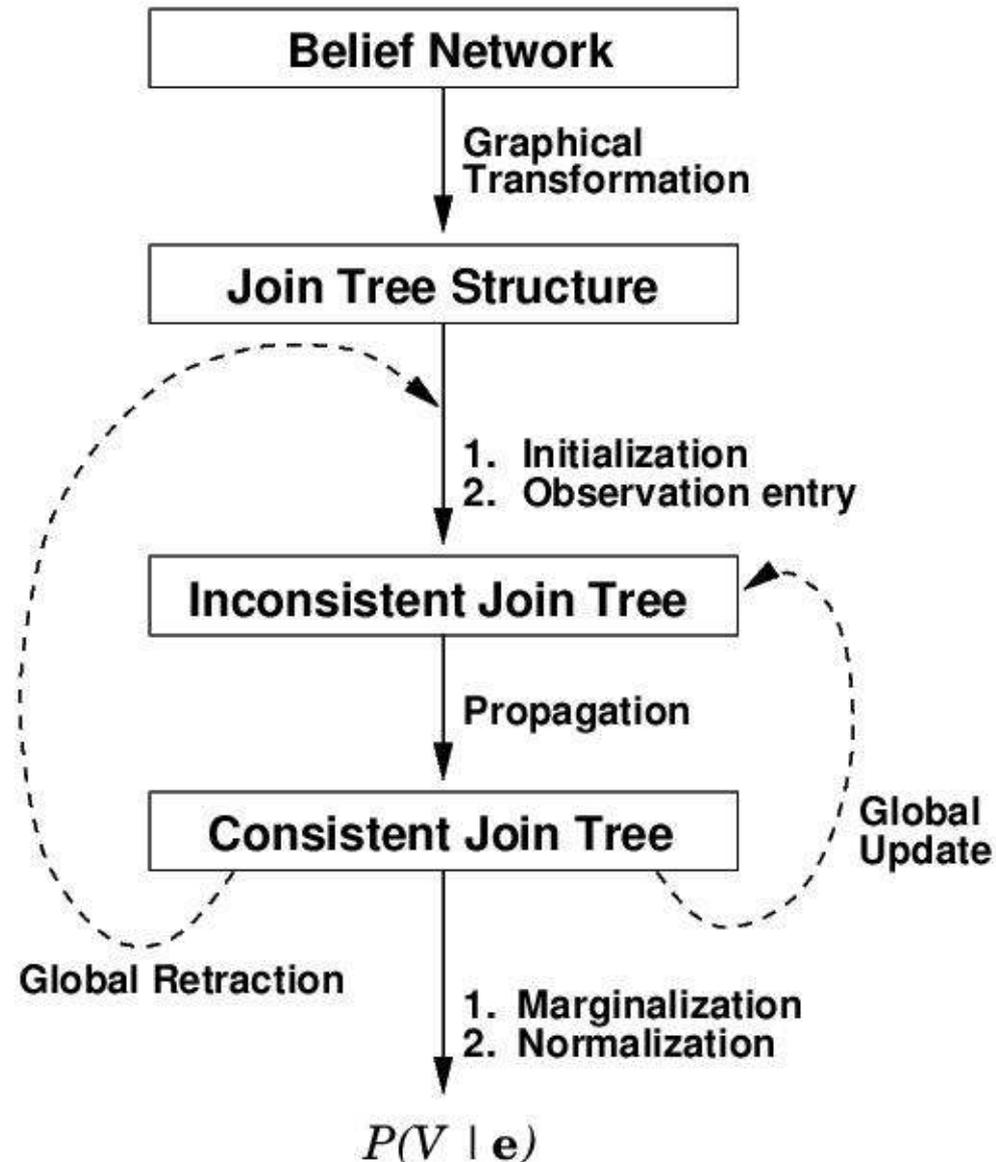
$$P(V | \mathbf{e}) = \frac{P(V, \mathbf{e})}{P(\mathbf{e})} = \frac{P(V, \mathbf{e})}{\sum_V P(V, \mathbf{e})}.$$

Handling evidence

Handling dynamic observations:

after computing $P(V | e_1)$,
we wish to compute $P(V | e_2)$..

we can directly **modify the join tree potentials** in response to changes in the set of observations.





Fine

Thank you!

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Identifying cliques:

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